Collaborative Parallel Grippers ECG2-30300 2-Finger

- ECG is a collaborative 2-finger parallel gripper that is equipped with symmetry in a second symmetry of the symmetry

- ROS compatible Designed for harsh environments Grip actuation via embedded controller. Brake locking mechanism.



SPECIFICATIONS

| Model | Stroke per Jaw | Gripping Force per Jaw | Total Gripping Force | Opening/ Closing Time | Nominal Voltage | Nominal Current | Max Current | Repeatability (Positioning) | Recommended Workpiece Weight* | Weight |
|------------|-------------------|------------------------------|-------------------------|-----------------------------|--------------------|--------------------|----------------|--------------------------------|-------------------------------------|---------|
| ECG2-30300 | 30 mm | 40 - 300 N | 80 - 600 N | 0.8/0.8 5 | 24 V DC ± 10% | 0.40 A | 2.00 A | ± 0.03 mm | 6.0 kg | 1.50 kg |
| | 1.18 in | 8.99 - 67.44 lb | 17.98 - 134.89 lb | | | | | \pm 0.001 in | 13.23 lb | 3.31 lb |

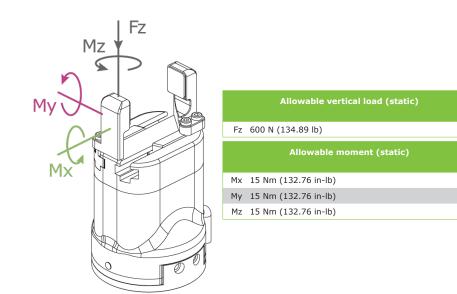
* Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

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Communication Interface Standard: Modbus RTU (RS485), Digital I/O
Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT
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IP Protection Class IP 67

Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

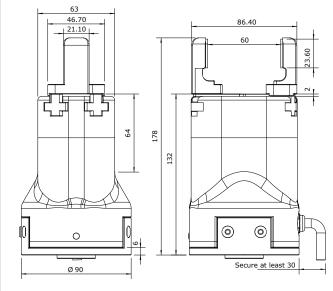
For this type of gripper the use of the standard fingers is recommended.

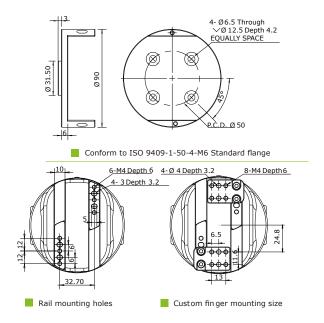




PRODUCT INFORMATION

ECG2-30300 2-Finger







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04.2022_Rev.01_EU