## **Collaborative Parallel Grippers** ECG2-30300 2-Finger

- ECG is a collaborative 2-finger parallel gripper that is equipped with symmetry in a second symmetry of the symmetry

- ROS compatible Designed for harsh environments Grip actuation via embedded controller. Brake locking mechanism.



## **SPECIFICATIONS**

Model	Stroke per Jaw	Gripping Force per Jaw	Total Gripping Force	Opening/ Closing Time	Nominal Voltage	Nominal Current	Max Current	Repeatability (Positioning)	Recommended Workpiece Weight*	Weight
ECG2-30300	30 mm	40 - 300 N	80 - 600 N	0.8/0.8 5	24 V DC ± 10%	0.40 A	2.00 A	± 0.03 mm	6.0 kg	1.50 kg
	1.18 in	8.99 - 67.44 lb	17.98 - 134.89 lb					$\pm$ 0.001 in	13.23 lb	3.31 lb

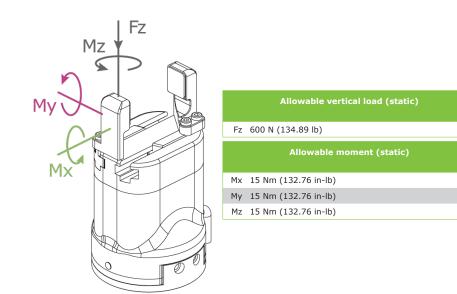
\* Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

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Communication Interface Standard: Modbus RTU (RS485), Digital I/O
Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT
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IP Protection Class IP 67

Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

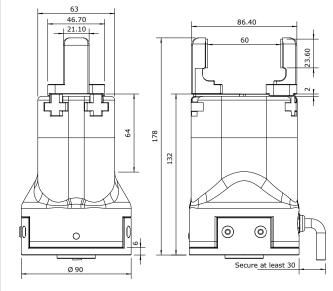
For this type of gripper the use of the standard fingers is recommended.

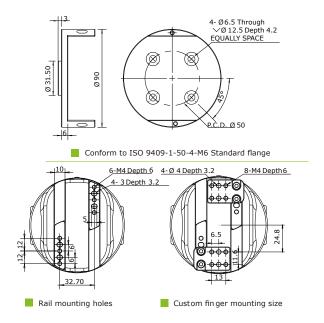




## **PRODUCT INFORMATION**

## ECG2-30300 2-Finger







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04.2022\_Rev.01\_EU