

Electric Parallel Grippers

EIG2-13015 2-Finger

EIG is an electric 2-finger parallel gripper that is equipped with two symmetrically parallel fingers.

Advantages

- Compact size
- Slim rectangular body with five installation positions for flexible mounting
- Grip control: force and position adjustment
- Quick open/close time with speed adjustment
- Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's
- Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter.
- Grip actuation via embedded controller.
- Brake locking mechanism on request.



SPECIFICATIONS

Model	Stroke per Jaw	Gripping Force per Jaw	Total Gripping Force	Opening/Closing Time	Nominal Voltage	Nominal Current	Max Current	Repeatability (Positioning)	Recommended Workpiece Weight*	Weight
EIG2-13015	13 mm 0.51 in	6 - 15 N 1.35 - 3.37 lb	12 - 30 N 2.7 - 6.74 lb	0.4 / 0.4 s	24 V DC ± 10%	0.25 A	0.50 A	± 0.02 mm ± 0.001 in	0.25 kg 0.55 lb	0.33 kg 0.73 lb

* Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

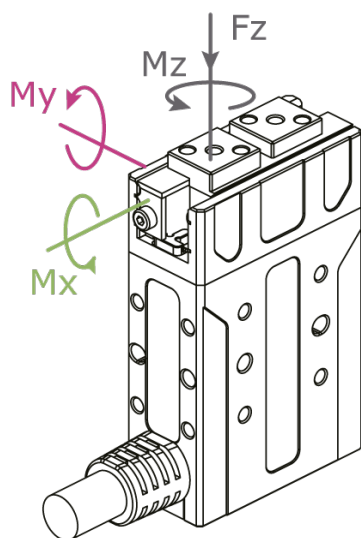
Communication Interface **Standard: Modbus RTU (RS485), Digital I/O**
Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class **IP 40**

Noise Emission (Sound Pressure) **≤ 40 dB(A) in any direction**

Recommended operating environment **0-40 °C (32-104 °F), < 85% RH**

For this type of gripper the use of the standard fingers is recommended.



Allowable vertical load (static)

Fz 70 N (15.74 lb)

Allowable moment (static)

Mx 0.9 Nm (7.97 in-lb)

My 0.75 Nm (6.64 in-lb)

Mz 0.9 Nm (7.97 in-lb)

